# Simultaneous Approximation and Birkhoff Interpolation II: The Periodic Case 

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## I. Introduction

We continue [6] by studying the simultaneous approximation of a realvalued function and its derivatives on the unit circle $K$. In order to do this, we will need a theorem giving sufficient conditions for the solvability of the Birkhoff interpolation problem in the periodic case.

Let $C_{i}(K)$ be the space of $i$-times continuously differentiable real-valued functions defined on the unit circle $K$. If $\|\cdot\|$ denotes the uniform norm on $C(K)$, then

$$
\|f\|_{k}=\max _{j=0,1, \ldots, k}\left\|f^{(j)}\right\|
$$

will be called the simultaneous norm. Here $f^{(j)}$ denotes the $j$ th derivative of $f$ in the clockwise direction.

Let $H$ be a finite-dimensional Chebycheff subspace of $C_{k}(K)$. We will investigate whether $f \in C_{k}(K)$ has a unique best approximation from $H$ with respect to $\|\cdot\|_{k}$. This is usually not the case and we will determine the precise dimension of the set $\Omega_{H}(f)$ of best simultaneous approximations to $f$ from $H$.

The ideas are similar to those in [6] but, due to the periodic nature of the functions involved, the structure of $\Omega_{H}(f)$ is particularly simple. In fact, it will be shown that the set of best approximations consists of either one point or is one-dimensional. This is in contrast to the algebraic case [6], in which the dimension of $\Omega_{H}(f)$ could have been as high as $k$ if the approximation was with respect to $\|\cdot\|_{k}$.

Let $A \subset C_{j}(K) . A^{(j)}$ will then denote the set

$$
A^{(j)}=\left\{a^{(j)} \mid a \in A\right\} .
$$

Our main theorem will be
Theorem 1. Let $H$ be an $N$-dimensional subspace of $C_{k+2}(K)$ such that each non-zero $h \in H^{(k+2)}$ has at most $N-1$ zeros. If $f \in C_{k+1}(K)$, then $\Omega_{H, k}(f)$, the set of best approximations to ffrom $H$ with respect to $\|\cdot\|_{k}$, has dimension at most one.

## II. The Periodic Birkhoff Interpolation Problem

In order to prove Theorem 1, we will need sufficient conditions for the regularity of the Birkhoff interpolation problem for periodic Chebycheff subspaces $H$ of dimension $N$ which satisfy the additional condition that no element of $H^{(k)}$ can have more than $N-1$ zeros. These assumptions on $H$ are more restrictive than one might assume at first glance, for

Lemma 2. Let $H$ be an $N$-dimensional subspace of $C_{k}(K)$ such that each non-zero $h \in H^{(k)}$ has at most $N-1$ zeros. Then
(1) $H$ is a Chebycheff space;
(2) $N$ is odd;
(3) $\operatorname{dim} H^{(i)}=N-1, i=1,2, \ldots, k$;
(4) each non-zero $h \in H^{(i)}$ has at most $N-1$ zeros, $i=1,2, \ldots, k$;
(5) the constant function belongs to $H$.

Proof. A very important, although elementary, fact about zeros of periodic functions is

Lemma 3. If $f \in C_{1}(K)$ has $N$ zeros, then $f^{\prime}$ also has at least $N$ zeros.
This is Rolle's theorem for periodic functions and explains why results for periodic systems differ so much from results for systems defined on intervals. Parts (1) and (4) of Lemma 2 follow from Lemma 3 immediately, for if any non-zero $f \in H^{(i)}, i=0,1, \ldots, k-1$, had $N$ or more zeros, then by repeated application of Lemma 3, $f^{(k-i)}$, which belongs to $H^{(k)}$, would also have at least $N$ zeros contradicting the assumption on $H^{(k)}$.

From (4) now follows that no non-zero $f \in H^{(1)}$ can have more than $N-1$ zeros. If the dimension of $H^{(1)}$ were $N$, then $H^{(1)}$ would be a Chebycheff space and therefore contains a strictly positive function (see [3] or [7]). But this is impossible since if $f \in H^{(1)}$, then $f=h^{\prime}$ for some $h \in H$ and

$$
\int_{0}^{2 \pi} f(t) d t=\int_{0}^{2 \pi} h^{\prime}(t) d t=h(2 \pi)-h(0)=0 .
$$

This is incompatible with $f(t)>0$ for all $t \in[0,2 \pi)$. Thus $\operatorname{dim} H^{(1)} \leqslant N-1$. Since the constant function is the only continuous solution to $h^{\prime}=0$ on $K$, it follows that the constant function belongs to $H$ and that $\operatorname{dim} H^{(1)}=$ $N-1$. Since the constant function is also the only continuous solution to $f^{(i)}=0$ on $K$, it also follows that $\operatorname{dim} H^{(i)}=N-1, i=1, \ldots, k$.

We have shown that $H$ is a Chebycheff subspace of dimension $N$. Then $N$ is necessarily odd since there exist no Chebycheff subspaces of even dimension on $K$ (see [7]).

Our theorem thus applies to a fairly restricted class of subspaces. One of these is the subspace $T_{n}$ of trigonometric polynomials. This was shown by Johnson [2]. Another example is the space of periodic algebraic polynomials $\mathscr{P}_{n, r}$, which we present here for the first time

$$
\mathscr{P}_{n, r}=\left\{P \in \Pi_{n} \mid P^{(i)}(0)=P^{(i)}(2 \pi), i=0,1, \ldots, r\right\} .
$$

$\Pi_{n}$ denotes the space of algebraic polynomials of degree not exceeding $n$. The proof that $\mathscr{P}_{n, r}$ is indeed an $n-r$ dimensional subspace of $C_{r}(K)$ which satisfies the conditions of Theorem 1 will be deferred to the end of our exposition.

The main tool used to prove Theorem 1 will be the theory of Birkhoff interpolation for periodic systems. The method of proof follows the same lines as for the trigonometric case as developed in [1].

Let $E=\left(e_{i j}\right)$ be an $m \times(n+1)$ matrix consisting of only zeros and ones. $E$ is called an incidence matrix. We will number the rows (which correspond to knots of interpolation) from 1 to $m$ and the columns (which correspond to the derivative being interpolated) from 0 to $n$. Let $H \subset C_{n}(K)$. The Birkhoff interpolation problem (B.I.P.) for $E$ and $H$ is to find an element $h \in H$ satisfying

$$
h^{(j)}\left(t_{i}\right)=b_{i j}
$$

for given data $b_{i j}$, knots $0 \leqslant t_{1}<\cdots<t_{m}<2 \pi$ and for those pairs $(i, j)$ such that $e_{i j}=1$. If there is a unique solution to this problem for each set of data and each choice of ordered knots, $E$ is said to be regular (with respect to $H$ ). Otherwise $E$ is singular. A sequence of $E$ of length $l$ is a maximal sequence of ones which has length $l$ and lies in some row of $E: e_{i, j}=0$, $e_{i, j+1}=\cdots=e_{i, j+l}=1, e_{i, j+l+1}=0$. The possibilities $j=-1$ and $j+l+1=$ $n+1$ are allowed. A sequence is called even or odd if it has even or odd length. The sequence given above is said to be (periodically) supported if some $e_{s, t}=1$ for $t \leqslant j$.

Theorem 4. Let $E$ be an $m \times(n+1)$ incidence matrix which has exactly $N$ ones, has at least one 1 in its 0 th column and which has no odd supported sequences. Suppose that $H \subset C_{n+1}(K)$ has dimension $N$ and that no
$g \in H^{(n+1)}$ has more than $N-1$ zeros without vanishing identically. Then $E$ is regular with respect to $H$. That is, the B.I.P. corresponing to $E$ always has a unique solution in $H$.

Moreover, if E satisfies the above conditions but has more than $N$ ones, the only solution to the homogeneous B.I.P. is the zero function.

Proof. We will show that the only solution to the homogeneous B.I.P. is the zero function. This implies that a unique solution to the B.I.P. with arbitrary data exists.

Let $m_{i}$ be the number of ones in the $i$ th column of $E$ and let $T=\left\{t_{1}, \ldots, t_{m}\right\}$ be given. Suppose that $h \in H$ satisfies the homogeneous B.I.P. for $E$. Then $h$ has $m_{0}$ zeros. By Rolle's theorem, unless $h \equiv 0, h^{\prime}$ has a sign change between each of the $m_{0}$ zeros of $h$. We would like to add to these, the $m_{1}$ zeros prescribed by $E$ to conclude that $h^{\prime}$ has $m_{0}+m_{1}$ zeros. But some of the $m_{0}$ zeros determined by Rolle's theorem may coincide with some of the $m_{1}$ zeros determined by $E$. If this is the case, we must analyse more carefully what happens. Then there are three knots $t_{i}<t_{j}<t_{k}$ such that $e_{i, 0}=e_{j, 1}=e_{k, 0}=1$ and $e_{l, 0}=0$ for $i<l<k$. Thus a supported begins at position ( $j, 1$ ). This sequence is, by assumption, even. But $h^{\prime}$ must change its sign between $t_{i}$ and $t_{k}$. Therefore, either $h^{\prime}$ has another zero between $t_{i}$ and $t_{k}$, or the zero $t_{j}$ must have a higher multiplicity. In the first case, we do not lose a zero when counting the zeros of $h^{\prime}$. In the second case, we may conclude that $h^{\prime}$ has a zero of multiplicity at least one more than the length of the sequence (inasfar as $h$ is sufficiently often differentiable). As we will be repeating this process, we will have lost a zero of $h^{\prime}$ but we will regain it at some higher derivative. Since such a coincidence can occur at most once for each sequence, the lost zero will be rewon at the latest when we have arrived at the $n+1$ st derivative.

Thus by repeating this process, we may conclude that $h^{(n+1)}$ has at least $m_{0}+m_{1}+\cdots+m_{n}=N$ zeros. Thus $h^{(n+1)} \equiv 0$. By Lemma 2, $\operatorname{dim} H^{(i)}=$ $N-1$ for $i=1,2, \ldots, n+1$. Therefore $h^{\prime} \equiv 0$ and so $h \equiv$ constant. But $h(t)=0$ at one of the knots, thus $h \equiv 0$ as desired.

If one assumes a little more about the zeros of the elements of $H^{(n)}$, then no assumption on $H^{(n+1)}$ is needed. The concept we use is that of the multiplicity of zeros, which may be found in Karlin and Studden [3]. Let $f \in C(K)$ or $f \in C(I)$, where $I$ is the closed interval $[a, b]$. Let $f(t)=0$. We say that $f$ has a zero of order one at $t \in K$ or $t \in[a, b]$ if $f$ changes sign at $t$ or if $t$ is one of the endpoints of $I$. We say that $f$ has a zero of multiplicity two if $f(s) \geqslant 0$ or $f(s) \leqslant 0$ in some neighborhood of $t$. $\tilde{Z}(f)$ will denote the number of zeros of $f$ counting multiplicities in this way.

It is well known that if $H \subset C(K)$ or $H \subset C(I)$ is a Chebycheff subspace of degree $n$, then $\tilde{Z}(f) \leqslant n-1$ for each $f \in H$. Moreover, for any $f \in C(K)$, $\tilde{Z}(f)$ is always an even number. The interesting feature of these con-
siderations is that a zero $t$ of $f$ may be counted with multiplicity two even though $f^{\prime}(t)$ may not exist.

Theorem 5. Let $E$ be an $m \times(n+1)$ incidence matrix which has exactly $N$ ones, has at least one 1 in its 0 th column and which has no odd supported sequences. Suppose that $H \subset C_{n}(K)$ has dimension $N$ and that no $g \in H^{(n)}$ has more than $N-1$ zeros counting multiplicities. Then $E$ is regular with respect to $H$.

If E satisfies the above conditions and has more than $N$ ones, then the only solution to the homogeneous B.I.P. corresponding to $E$ is the zero function.

The proof follows that of Theorem 4 except that one may only conclude that an $h$ satisfying the homogeneous B.I.P. has an $n$th derivative which has at least $N$ zeros counting multiplicities. The main new technical difficulty occurs when, while counting zeros, a new zero is to be added to a sequence ending in the $n$th column. A satisfactory treatment of this difficulty may be found in Keener [4].

A particularly simple case in which the hypothesis is satisfied is if $G=\operatorname{span}\left\{1, H^{(n)}\right\}$ is a Chebycheff space of dimension $N$ (if $\operatorname{dim} H=N$ ). Then no element of $G$ and hence no element of $H^{(n)}$ can have more than $N-1$ zeros counting multiplicities. It will be shown later that this holds for $\mathscr{P}_{n, r}$ the set of periodic algebraic polynomials. There are some hints that this favorable circumstance is not improbable. Firstly, for any $H$ satisfying the conditions of Theorem 5, the constant function can never belong to $H^{(n)}$ so that dim $\operatorname{span}\left\{1, H^{(n)}\right\}=N$ always. Secondly, the following lemma, whose proof follows easily from Lemma 3, holds.

Lemma 6. Let $H$ be an $N$-dimensional subspace of $C_{n}(K)$ such that no non-zero element of $H^{(n)}$ has more than $N-1$ zeros. Then span $\left\{1, H^{(i)}\right\}$ is an $N$-dimensional Chebycheff subspace of $C_{n-i}(K)$ for $i=1, \ldots, n-1$.

## III. Simultaneous Approximation

We may use these results on the periodic B.I.P. to characterize the dimension of the set of best approximations to a function with respect to a simultaneous norm.

We defined

$$
\|f\|_{k}=\max _{j=0,1, \ldots, k}\left\|f^{(j)}\right\|
$$

for $f \subset C_{k}(K)$. Let $H \subset C_{k}(K)$. Then we denote by $\Omega_{H, k}(f)$ (or by $\Omega_{H}(f)$ ), the set of best approximations to $f$ from $H$ with respect to $\|\cdot\|_{k}$ and by
$E_{H, k}(f)$ the degree of approximation to $f$ from $H$. Then for each $h \subset \Omega_{H}(f),\|f-h\|_{k}=E_{H, k}(f)$. By $U_{j}(f, h)$, we denote the extremal sets of the approximation $h$ to $f$

$$
U_{j}(f, h)=\left\{t \in K \mid\left\|f^{(j)}-h^{(j)}\right\|=\|f-h\|_{k}\right\}
$$

for $j=0,1, \ldots, k$. The extremal sets are compact and at least one of them is non-empty. Since $\Omega_{H}(f)$ is convex, it has a relative interior and a relative dimension. $\operatorname{dim} \Omega_{H}(f)$ will denote the relative dimension of $\Omega_{H}(f)$. Any element of $H$ lying in the relative interior of $\Omega_{H}(f)$ will be called a minimal best approximation (to $f$ ). This terminology is motivated by

Lemma 7. If $h$ is a minimal best approximation to $f$, then for any other best approximation $g$,

$$
U_{j}(f, h) \subset U_{j}(f, g), \quad j=0,1, \ldots, k
$$

Thus the extremal sets of a minimal best approximation are the smallest possible. It follows immediately that for any two minimal best approximations $h, g$ to $f$, we have $U_{j}(f, h)=U_{j}(f, g), j=0,1, \ldots, k$. These common sets will be denoted by $U_{j}(f)$ and will be called the extremal sets of $f$ since they depend only on $f$ and $H$ and not on the choice of a minimal best approximation.

Lemma 8. We have

$$
U_{j}(f) \cap U_{j+1}(f)=\varnothing, \quad j=0,1, \ldots, k-1
$$

and if $g, h \in \Omega_{H}(f), f \in C_{k+1}(K)$ and $H \subset C_{k+1}(K)$, then

$$
\begin{aligned}
g^{(j)}(t) & =h^{(j)}(t), & & t \in U_{j}(f) \\
g^{(j+1)}(t) & =h^{(j+1)}(t), & & t \in U_{j}(f)
\end{aligned}
$$

for all $j=0,1, \ldots, k$.
The fact that two best approximations must coincide on so many points yields the uniqueness theorem.

Theorem 9. Let $H$ be an $N$-dimensional subspace of $C_{k+2}(K)$ such that no non-zero element of $H^{(k+2)}$ has more than $N-1$ zeros. Let $f \in C_{k+1}$. If $U_{0}(f) \neq \varnothing$, then the best approximation to from $H$ with respect to $\|\cdot\|_{k}$ is unique. If $U_{0}(f)=\varnothing$, then $\operatorname{dim} \Omega_{H, k}(f)=1$. In any case, $\operatorname{dim} \Omega_{H, k}(f) \leqslant 1$.

Proof. Let $h$ be a minimal best approximation to $f$ and $g$ be any other element of $\Omega_{H}(f)$. By Lemma 8,

$$
\begin{aligned}
(h-g)^{(j)}(t) & =0 \\
(h-g)^{(j+1)}(t) & =0
\end{aligned}
$$

for $t \in U_{j}(t), j=0,1, \ldots, k$. Let $E$ be the incidence matrix corresponding to these conditions. We will show that $E$ contains at least $N$ ones. By Lemma 8, we know that the pairs of conditions appearing above cannot overlap each other. Thus $E$ has only even sequences. If therefore $E$ had $M \leqslant N-1$ ones, we could add $N-M$ new ones to the 0 th column (adding new knots if necessary) to obtain an incidence matrix $\bar{E}$ satisfying the conditions of Theorem 4. It follows that there is a $u \in H$ satisfying

$$
u^{(j)}(t)=\sigma(h(t)-f(t))
$$

for $t \in U_{j}(t), j=0,1, \ldots, k$, where $\sigma(t)$ is the sign of $t$. But then $h-\varepsilon u$, for all $\varepsilon>0$ sufficiently small, is a better approximation to $f$ than $h$ is. This is by assumption not possible, so $M \geqslant N$.

As in the proof of Theorem 4, $(h-g)^{(k+1)}$ has $M$ zeros and therefore $(h-g)^{(k+1)} \equiv 0$. Since $\operatorname{dim} H^{(1)}=\operatorname{dim} H^{(k+1)},(h-g)^{\prime} \equiv 0$ and so $h-g$ is a constant. If $U_{0}(f) \neq \varnothing$, then $(h-g)(t)=0$ at one of the knots which implies that $h-g \equiv 0$ and that $\Omega_{H, k}(f)=\{h\}$. If $U_{0}(f)=\varnothing$, then $h+c \in \Omega_{H}(f)$ for all constants $c$ such that $|c|$ is sufficiently small.

Theorem 10. Let $H$ be an $N$-dimensional subspace of $C_{k+1}(K)$ such that no non-zero element of $H^{(k+1)}$ can have more than $N-1$ zeros counting multiplicities. Let $f \in C_{k+1}(K)$. If $U_{0}(f) \neq \varnothing$, then the best approximation to $f$ from $H$ with respect to $\|\cdot\|_{k}$ is unique. If $U_{0}(f)=\varnothing$, then $\operatorname{dim} \Omega_{H, k}(f)=1$. In any case, $\operatorname{dim} \Omega_{H, k}(f) \leqslant 1$.

## IV. An Example

By $\mathscr{P}_{n, r}$, we denote the space of periodic algebraic polynomials:

$$
\mathscr{P}_{n, r}=\left\{P \in \Pi_{n} \mid P^{(i)}(0)=P^{(i)}(2 \pi), \quad i=0,1, \ldots, r\right\}
$$

We will show that if $n-r$ is odd, then $\mathscr{P}_{n, r}$ satisfies the assumptions of Theorem 10 with $N=n-r$ and for any $k \leqslant r-1$.

Lemma 11. Let $\mathscr{P}_{n, r}$ be the space of periodic algebraic polynomials defined above. Suppose $n-r$ is odd.

## Then

(1) $\operatorname{dim} \mathscr{P}_{n, r}=n-r$;
(2) $\mathscr{P}_{n, r}$ is a Chebycheff subspace of $C_{r}(K)$;
(3) for each $i, 0 \leqslant i \leqslant r$, no element of $\mathscr{P}_{n, r}^{(i)}$ can have more than $n-r-1$ zeros counting multiplicities.

Proof. We will first show that if $n-r$ is odd, then no element of $\mathscr{P}_{n, r}^{(i)}$ can have more than $n-r-1$ zeros counting multiplicities for $i=0,1, \ldots, r$. Due to Lemma 3, it suffices to show this for $i=r$; i.e., to show that for each $P \in \mathscr{P}_{n, r}^{(r)}, \tilde{Z}(P) \leqslant n-r-1$. The elements of $\mathscr{P}_{n, r}^{(r)}$ are polynomials $P$ of degree not exceeding $n-r$ and for which $P(0)=P(2 \pi)$. Suppose that some polynomial $P$ had $\tilde{Z}(P) \geqslant n-r$. Since $n-r$ is odd, $\tilde{Z}(P) \geqslant n-r+1$ since $\tilde{Z}(P)$ is always even. We will now consider $P$ as being defined on $I=[0,2 \pi]$. Let $\tilde{Z}_{K}(P)$ (respectively $\tilde{Z}_{I}(P)$ ) be the number of zeros of $P$ counting multiplicities when defined on $K$ (respectively when defined on $I=[0,2 \pi])$. It can easily be seen that $\tilde{Z}_{K}(P) \leqslant \tilde{Z}_{I}(P)$. But $\tilde{Z}_{K}(P) \geqslant$ $n-r+1$ so that also $\tilde{Z}_{l}(P) \geqslant n-r+1$. Since $P \in \Pi_{n-r}, P \equiv 0$. This proves (3).

By definition, $\mathscr{P}_{n, r}$ is a subspace consisting of those elements of the $n+1$ dimensional space $\Pi_{n}$ which satisfy $r+1$ linear conditions. Thus dim $\mathscr{P}_{n, r} \geqslant n-r$. But, if $n-r$ is odd, we have just shown that no element of $\mathscr{P}_{n, r}$ can have more than $n-r-1$ zeros. Therefore $\mathscr{P}_{n, r}$ is a Chebycheff subspace and $\operatorname{dim} \mathscr{P}_{n, r}=n-r$ which proves (1).

Since, by definition, all elements of $\mathscr{P}_{n, r}$ have periodic derivatives of order up to $r$, (2) has also been shown.

An interesting aspect of this proof is that absolutely no calculations were needed to show that $\operatorname{dim} \mathscr{P}_{n, r}=n-r$. An alternative proof would have been to show that the $r+1$ linear conditions determining $\mathscr{P}_{n, r}$ are linearly independent (which is not hard to do). Then $\operatorname{dim} \mathscr{P}_{n, r}=n-r$ follows immediately (even if $n-r$ is even).

Corollary 12. Let $f \in C_{k+1}(K)$. Let $n \geqslant r \geqslant 0, n-r$ be odd and $k \leqslant r-1$. Then the dimension of the set of best approximations from $\mathscr{P}_{n, r}$ to $f$ with respect to $\|\cdot\|_{k}$ does not exceed 1 . In particular, if $U_{0}(f) \neq \varnothing$, the best approximation is unique. If $U_{0}(f)=\varnothing$, the set of best approximations has dimension exactly one.

Corollary 13. For $1 \leqslant i \leqslant r$,

$$
\operatorname{span}\left\{1, \mathscr{P}_{n, r}^{(i)}\right\}=\mathscr{P}_{n-i, r-i}
$$

## V. Concluding Remarks

As in [6], the norm of simultaneous approximation could have been chosen to be

$$
\|f\|_{F}=\max _{i=1, \ldots, p}\left\|f^{\left(k_{i}\right)}\right\|
$$

where $0 \leqslant k_{1}<k_{2}<\cdots<k_{p}$. For this semi-norm, the formulation of Theorems 9 and 10 and their proofs remain the same.

The assumption that $f \in C_{k+1}(K)$, which was made in Theorems 9 and 10 , appears unnatural since the norm $\|\cdot\|_{k}$ involves derivatives of order only up to $k$. The theorems are, however, false without this assumption as can be seen by example given in [2].

Theorems 4 and 5 on the regularity of the periodic B.I.P. are not sharp of course because they only give necessary conditions for regularity. By comparing these general theorems with their trigonometric counterparts [1], one sees which of the assumptions are indispensable.

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